INFORMATION RETRIEVAL

Language models

Corso di Laurea Magistrale in Informatica

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Derived from slides originally produced by C. Manning and by H. Schütze

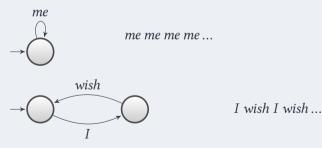


- We view the document in terms of as a generative model that generates the query
- What we need to do:
 - Define the precise generative model we want to use
 - Estimate parameters (different parameters for each document's model)
 - Smooth to avoid zeros
 - · Apply to query and find document most likely to have generated the query
 - Present most likely document(s) to user

What is a language model?

- \odot Assume we are reading (or generating) a document *d* term by term
- We can view a language model M_d for d as a way to determine the next term which will be read (generated)

We can view the language model as a finite state automaton, where the transitions between states are associated to terms



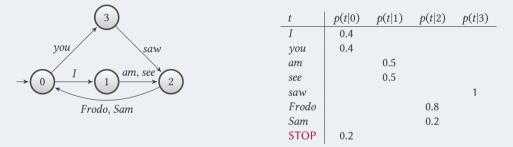
Cannot generate: "I I", " wish wish wish" or "wish I wish": history counts

Each document was generated by a different automaton like this, except that these automata are probabilistic.

- For each node, a probability distribution is defined on all transitions
- A document corresponds to (is generated as) a sequence of random sample on such distributions

A probabilistic language model

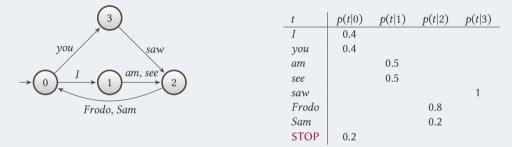




- This is a probabilistic finite-state automaton and the transition distribution for its states 0, 1, 2, 3.
- **STOP** is not a word, but a special symbol indicating that the automaton stops.

A probabilistic language model

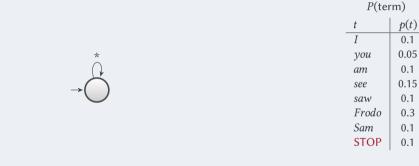
P(term|state)



• possible sequence generated:
$$\frac{w}{P(t|s)} = 0.4$$
 0.5 0.8 0.4 1 0.2 0.2
Total sequence probability = 0.00256

A probabilistic unigram language model

A simple version of language models, that we will consider here, is provided by the case when there is a unique state, hence p(t|s) = p(t) for each term



o possible sequence generated:

	W	Frodo	Ι	Sam	Sam	saw	see	Frodo	STOP
	P(t s)	0.3	0.1	0.1	0.1	0.15	0.2	0.3	0.1
Total sequence probability = $2.7 \cdot 10^{-7}$									

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A different language model for each document

M_{d_1} : language model of d_1				M_{d_1} :	M_{d_1} : language model of d_1			
t	p(t)	t	p(t)	t	p(t)	t	p(t)	
STOP	.1	I	.15	STOP	.2	1	.1	
you	.2	am	.05	you	.1	am	.05	
see	.05	saw	.05	see	.15	saw	.2	
Frodo	.2	Sam	.2	Frodo	.15	Sam	.05	

query: Frodo saw Sam STOP

 $p(query|M_{d1}) = 0.2 \cdot 0.05 \cdot 0.2 \cdot 0.1 = 2 \cdot 10^{-4}$ $p(query|M_{d2}) = 0.15 \cdot 0.2 \cdot 0.05 \cdot 0.2 = 3 \cdot 10^{-4}$

 $p(query|M_{d1}) < p(query|M_{d2})$: thus, document d_2 is "more relevant" to the query "Frodo saw Sam STOP" than d_1 is.

- Each document is treated as (the basis for) a language model.
- \odot Given a query *q*:
 - We wish to rank documents by

$$p(d|q) = \frac{p(q|d)p(d)}{p(q)}$$

- p(q) is the same for all documents, so ignore
- p(d) is the prior often treated as the same for all d
 - But we could give a higher prior to documents which are relevant wrt some other measure, e.g., those with high PageRank.
- p(q|d) is the probability of q given d
- For uniform prior: ranking documents according to p(q|d) and p(d|q) is equivalent.

We may see p(q|d) as the probability that the document the user had in mind when she was formulating the query was in fact this one.

- In the LM approach to IR, we attempt to model the query generation process.
- Then we rank documents by the probability that a query would be observed as a random sample from their respective document models (probability distributions)
- That is, we rank according to P(q|d).
- In general, a document model structure (type of probability distribution) is assumed and its parameters values are derived, for each document, from its content

We make the Naive Bayes conditional independence assumption:

$$p(q|M_d) = p(\langle w_1, \dots, w_{|q|} \rangle |M_d) = \prod_{i=1}^{|q|} p(w_k|M_d)$$

|q|: length of q; w_k : token t occurring at position k in q

Where do the parameters $p(w_k|M_d)$ come from?

• Likelihood: this is the probability of data given a model, in this case $p(q|M_d)$

- For fixed data, this provides a measure associated to each model instance (parameter values): the probability that such data are generated in the probabilistic framework defined by the model instance (for example, probability distribution)
- This can be seen as "how much" a model instance explains the given data

How to compute P(q|d)

An hypothesis on the model structure (and the generation process) must be assumed.

- hypothesis: all terms have an associated probability to be the next word generated; this probability is independent from previous occurrences
- \odot the probability of observing *k* occurrences of term *t* in the query *q* is given by the binomial distribution

$$p(tf_{t,q} = k) = \frac{|q|!}{k!(|q|-k)!}p^k(1-p)^{|q|-k}$$

• the probability of observing $k_1, k_2, ..., k_m$ occurrences of all terms $t_1, ..., t_m$ in the query q is given by the multinomial distribution

$$p(tf_{t_i,q} = k_i, i = 1, ..., m) = \frac{|q|!}{\prod_{i=1}^m k_i!} \prod_{i=1}^m p_i^{k_i}$$

 \odot That is, for each document *d*,

$$p(\mathrm{tf}_{t_i,q} = k_i, i = 1, \dots, m | M_d) \approx \prod_{t \in q} p(t | M_d)^{\mathrm{tf}_{t,q}}$$

since the multiplying factor

$$\frac{|q|!}{\prod_{i=1}^m \mathrm{tf}_{t_i,q}!}$$

is independent from the document

 \odot here M_d is an *m*-dimensional array

$$M_d = [p_1, p_2, \dots p_m]$$

with $\sum_{i=1}^{m} p_i = 1$ and $p(t_i|M_d) = p_i$

 The probability of the term in the document model, estimated by maximum likelihood is

$$\hat{p}_i = \hat{p}(t_i|M_d) = \frac{\mathrm{tf}_{t_i,d}}{|d|}$$

- \odot |*d*|: length of *d*
- \odot tf_{*t*_{*i*},*d*}: #occurrences of *t*_{*i*} in *d*

Different models

Different hypotheses on the distribution (generative process) provide different estimations.

 Multiple Poisson: we assume a dependancy exists between occurrences of a term. This is formalized by a Poisson distribution

$$p(\mathrm{tf}_{t,q} = k) = \frac{e^{-\lambda |q|} (\lambda |q|)^k}{k!}$$

where $\lambda |q|$ is the expected number of occurrences of *t* in *q* \odot for the whole guery

$$p(\mathsf{tf}_{t_i,q} = k_i, i = 1, \dots, m | M_d) = \prod_{i=1}^m \frac{e^{-\lambda_i |q|} (\lambda_i |q|)^{k_i}}{k_i!}$$

• here M_d is an *m*-dimensional array

$$M_d = [\lambda_1, \lambda_2, \dots \lambda_m]$$

- ◎ We have a problem with zeros: a single *t* with $p(t|M_d) = 0$ will make $p(q|M_d) = \prod p(t|M_d) = 0$
- We would give a single term "veto power".
- For example, for query [Frodo goes to mount Doom] a document about "Frodo Sam Doom" would have $p(q|M_d) = 0$
- We need to smooth the estimates to avoid zeros.

- Key intuition: A nonoccurring term is possible (even though it didn't occur), so we don't want to assign 0 probability to it
- We may avoid the zero probability case by adding a constant value, such as 1, to the count $tf_{t,d}$ in the maximum likelihood estimation: the numerator of the estimation ratio is now $tf_{t,d} + 1$
- ◎ This eliminates the zero probability case, but makes the normalization wrong, that is $\sum_t \text{tf}_{t,d} > |d|$. This can be avoided by summing *M*, the overall number of terms to |d| at the denominator

$$\hat{p}(t|M_d) = \frac{\mathrm{tf}_{t,d} + 1}{|d| + M}$$

- We may estimate its probability of a term in a document model by looking at the whole collection
- \odot Let us consider the collection model M_c the collection model: we may estimate
- The maximum likelihood estimate of the probability of the term in the whole collection is given by

$$\hat{p}(t|M_c) = \frac{\mathrm{cf}_t}{T}$$

where cf_t is the number of occurrences of *t* in the collection and $T = \sum_t cf_t$ is the total number of tokens in the collection.

• We will use (the estimate of) $\hat{p}(t|M_c)$ to "smooth" (the estimate of) p(t|d) away from zero.

The estimated probability of the term wrt the document is defined as a linear combination of the probability according to the document model and the probability according to the collection model

$$p(t|d) = \lambda p(t|M_d) + (1 - \lambda)p(t|M_c)$$

 λ is a hyper-parameter which tunes the relevance of the document model wrt the collection model

- Mixtures of two distributions
- \odot Correctly setting λ is very important for good performance

Assuming the conditional independence of terms,

$$p(q|d) = \prod_{1 \le k \le |q|} \left(\lambda p(t_k | M_d) + (1 - \lambda) p(t_k | M_c) \right)$$

- Basic idea: we model the case that the user has a document in mind and generates the query from this document.
- High value of λ: "conjunctive-like" search tends to retrieve documents containing all query words.
 - Low value of λ : more disjunctive, suitable for long queries

Example

Collection:

*d*₁: "Frodo and Sam reached mount Doom with the help of Gollum"
*d*₂: "Gollum was attracted by the One Ring"

Query q: "Gollum Ring"

- \odot Use mixture model with $\lambda = 1/2$
- \odot $|d_1| = 11, |d_2| = 7, T = 18$
- ◎ $P(q|d_1) = [(1/11 + 2/18)/2] \cdot [(0/11 + 1/18)/2] = \approx 0.0028$
- ◎ $P(q|d_2) = [(1/7 + 2/18)/2] \cdot [(1/7 + 1/18)/2] \approx 0.0125$

⊙ Ranking: $d_2 > d_1$

- Collection: d_1 and d_2
- \odot d_1 : Frodo had a small sword and a coat
- \odot d_2 : The Shire was a small region in the west of Middle Earth
- \odot Query *q*: west small
- Use mixture model with $\lambda = 1/2$
- \odot $|d_1| = 8, |d_2| = 12, T = 20$

t	tf_{t,d_1}	tf_{t,d_2}	cf_t	
west	0	1	1	
small	1	1	2	

- ◎ BM25/LM: based on probability theory
- o Vector space: based on similarity, a geometric/linear algebra notion
- Term frequency is directly used in all three models.
 - LMs: raw term frequency, BM25/Vector space: more complex
- \odot Length normalization
 - · Vector space: document vectors normalized
 - · LMs: probabilities are inherently length normalized
 - BM25: tuning parameters for optimizing length normalization
- \odot idf: BM25/vector space use it directly.
- ◎ LMs: Mixing term and collection frequencies has an effect similar to idf.
 - Terms rare in the general collection, but common in some documents will have a greater influence on the ranking.
- Collection frequency (LMs) vs. document frequency (BM25, vector space)