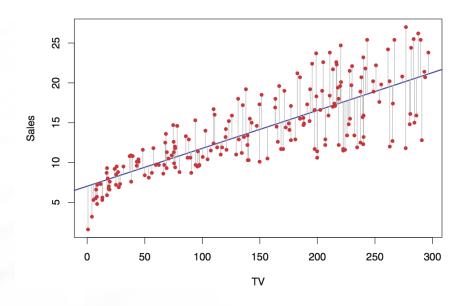




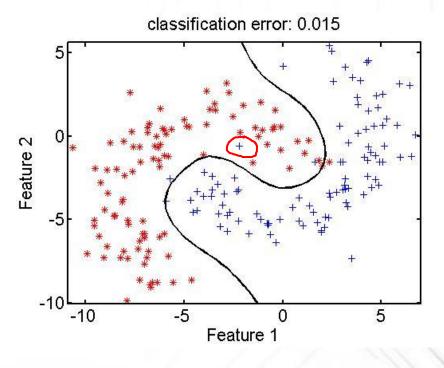
- Target problems for Machine Learning
- Geometrical Paradigms
- Probabilistic Paradigms
 - Generative models
 - Applications to speech and language processing

Machine Learning: the core problems

Regression

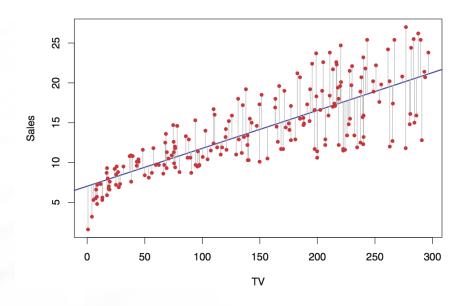


Classification

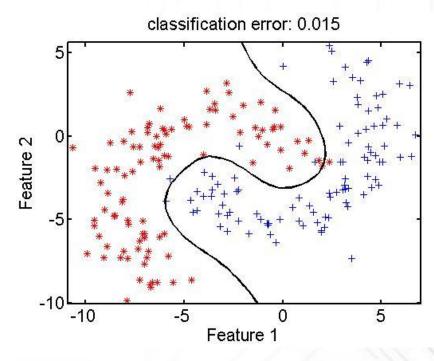


Machine Learning: the core problems

Regression



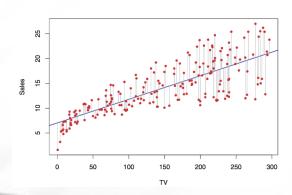
Classification



Machine Learning: the core problems

Regression

- Given a set of examples of a target function f(.)
- $x_1, ..., x_k$ with $y_i = f(x_i)$ known for every i
- Define a function *h(.)* such that:
 - $h(x_i) = y_i = f(x_i) \quad \forall i$
 - $h(x) \approx f(x)$ elsewhere

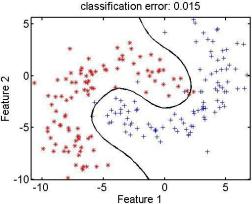


Classification

- Given n classes C_1 , ... C_n and a given number of instances x_1 , ..., x_k whose classification y_1 , ..., y_k (with $y_k \in \{C_1, ..., C_n\}$ is known
- Define the class membership function h(.) such that
 - $h(x_i) = y_i \quad \forall i = 1, ..., k$

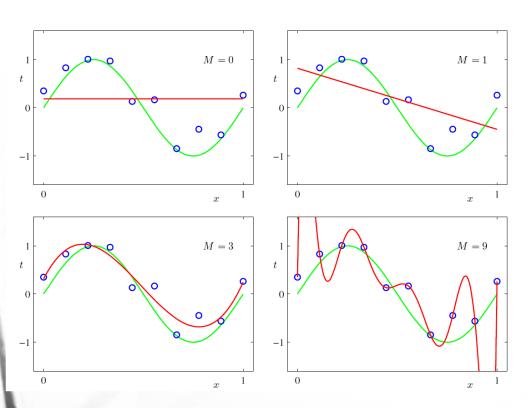
• $h(\underline{x}) \stackrel{\triangle}{=} C_i$ such that (by definition)

 $x \in C_i$ for all other x

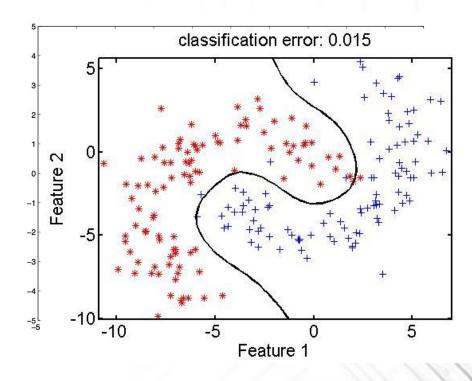


Machine Learning: Selecting the function

Regression



Classification

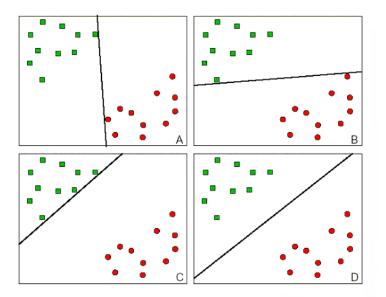


Paradigms for Model Selection

- Model Selection depends on the choice of:
 - (**Model Family Selection**) a class/family of functions (e.g. polynomials of degree *n*)
 - (Model parametrization). Selection/Estimation of the parameters suitable for defining the optimal decision function
 - Definition of the notion of optimality (e.g. coverage vs. accuracy)
 - Search for the optimal values of the parameters
 - Analytical forms
 - Empirical induction from the training set

Model Selection from a family of functions

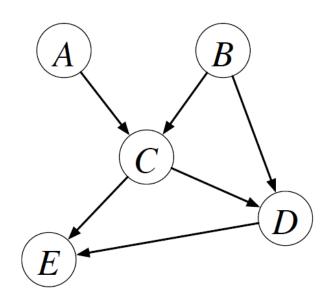
- Discriminative approaches
 - Linear models
 - $h(x) = sign(\mathbf{W} \cdot \mathbf{x} + \mathbf{b})$



- Probabilistic approaches
 - Estimates of probabilities probabilità $p(\mathcal{C}_k|\mathbf{x})$ over a training set
 - Generative Model of the target task allows the application of the Bayesin inversion

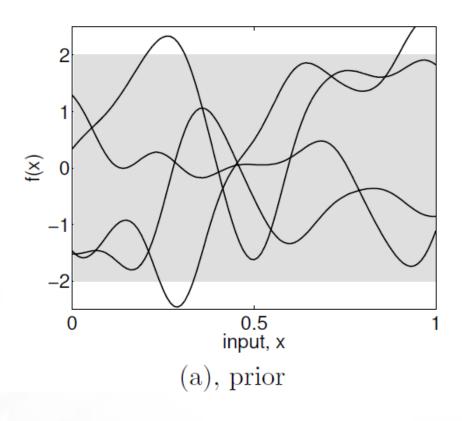
$$p(C_k|\mathbf{x}) = \frac{p(\mathbf{x}|C_k)p(C_k)}{p(\mathbf{x})}.$$

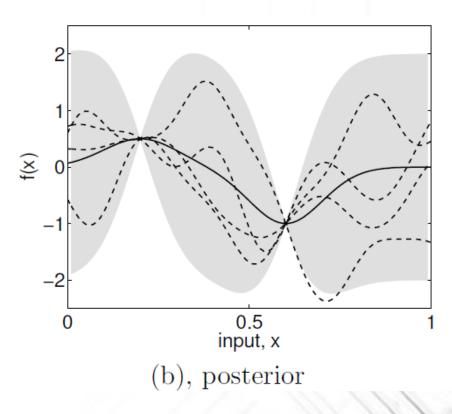
Graphical Models



$$p(A, B, C, D, E) = p(A)p(B)p(C|A, B)p(D|B, C)p(E|C, D)$$

Bayesian & Grafical models





Weighted Grammars: Languages, Syntax & Statistics

POS tagging (Curch, 1989)

- Probabilistic Context-Free Grammars (Pereira & Schabes, 1991)
- Data Oriented Parsing (Scha, 1990)
- Stochastic Grammars (Abney, 1993)
- Lexicalized Models (C. Manning, 1995)

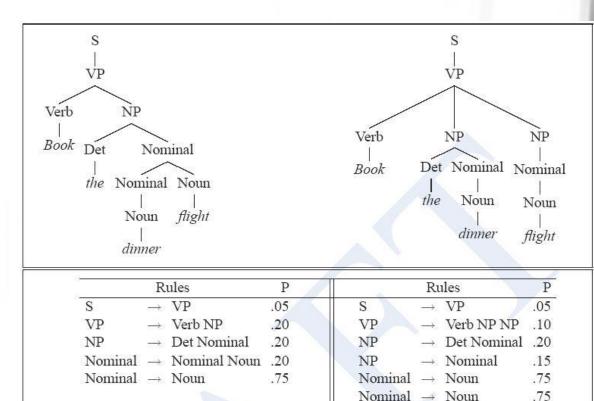


Figure 13.2 Two parse trees for an ambiguous sentence, The transitive parse (a) corresponds to the sensible meaning "Book flights that serve dinner", while the ditransitive parse (b) to the nonsensical meaning "Book flights on behalf of 'the dinner'?".

.30

.60

.10

.40

Verb

Det

Noun

Noun

→ book

→ dinner

→ flights

 \rightarrow the

.30

.60

.10

.40

 \rightarrow book

→ dinner

→ flights

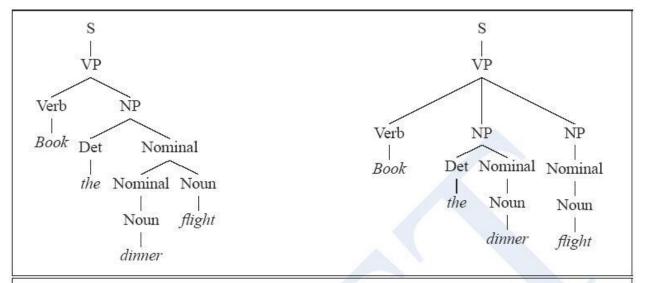
 \rightarrow the

Verb

Noun

Noun

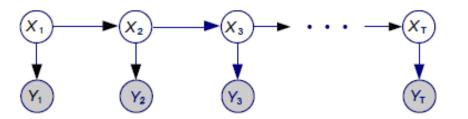
Weighted Grammars, between Syntax & Statistics



Rules			P	Rules			P
S	\rightarrow	VP	.05	S	\rightarrow	VP	.05
VP	\rightarrow	Verb NP	.20	VP	\rightarrow	Verb NP NP	.10
NP	\rightarrow	Det Nominal	.20	NP	\rightarrow	Det Nominal	.20
Nominal	\rightarrow	Nominal Noun	.20	NP	\longrightarrow	Nominal	.15
Nominal	\rightarrow	Noun	.75	Nominal	\rightarrow	Noun	.75
				Nominal	\rightarrow	Noun	.75
Verb	\rightarrow	book	.30	Verb	\rightarrow	book	.30
Det	\rightarrow	the	.60	Det	\rightarrow	the	.60
Noun	\rightarrow	dinner	.10	Noun	\rightarrow	dinner	.10
Noun	\rightarrow	flights	.40	Noun	\rightarrow	flights	.40

Figure 13.2 Two parse trees for an ambiguous sentence, The transitive parse (a) corresponds to the sensible meaning "Book flights that serve dinner", while the ditransitive parse (b) to the nonsensical meaning "Book flights on behalf of 'the dinner'?".

Hidden Markov Models

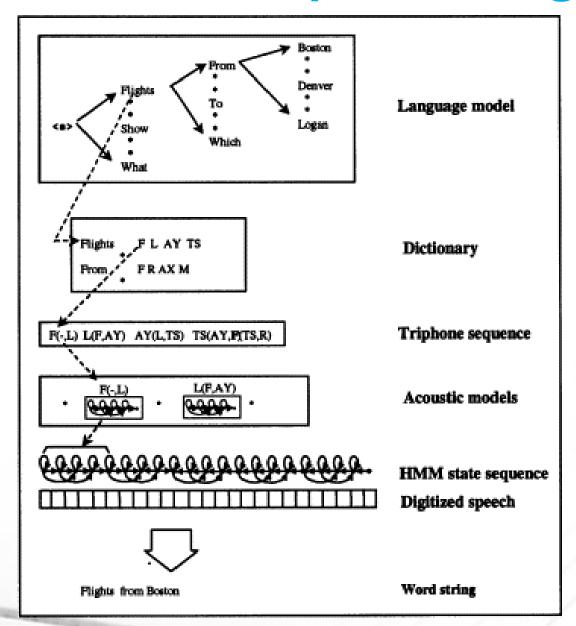


$$p(X_{1,\dots,T}, Y_{1,\dots,T}) = p(X_1)p(Y_1|X_1) \prod_{t=2}^{T} [p(X_t|X_{t-1})p(Y_t|X_t)]$$

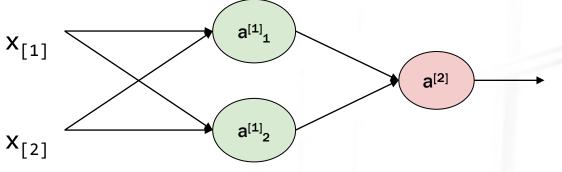
- States = Categories/Concepts/Properties
- Observations: (sequences of) symbols characterizing a given language

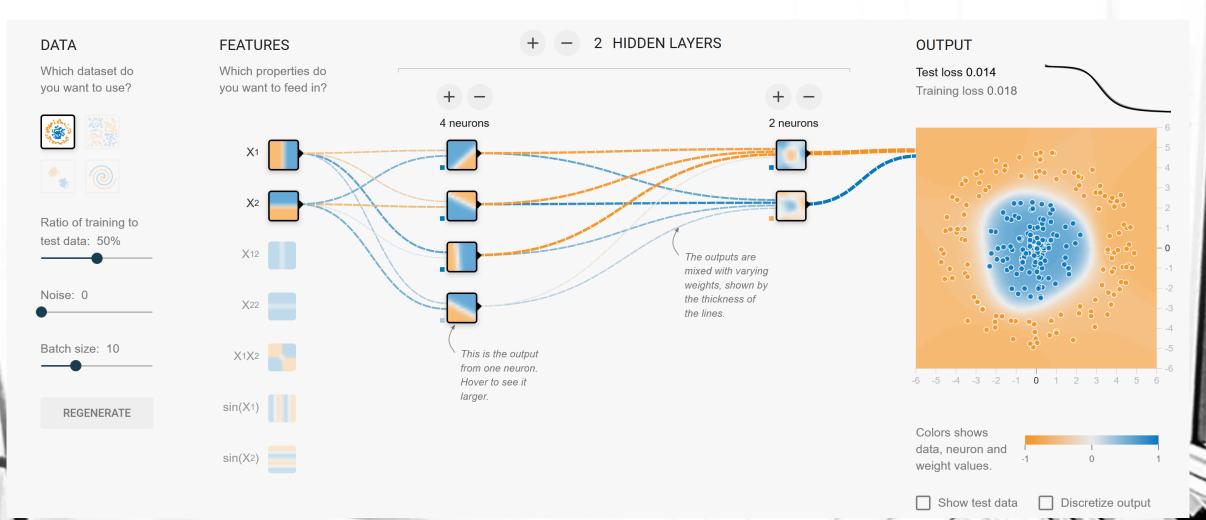
- Emissions (of symbols by States) vs. Transitions (between states)
- Applications:
 - Speech Recognition (symbols: phonems, states: segments of audio signal)
 - POS tagging (symbols: words, states: grammatical categories, i.e. POS tags)

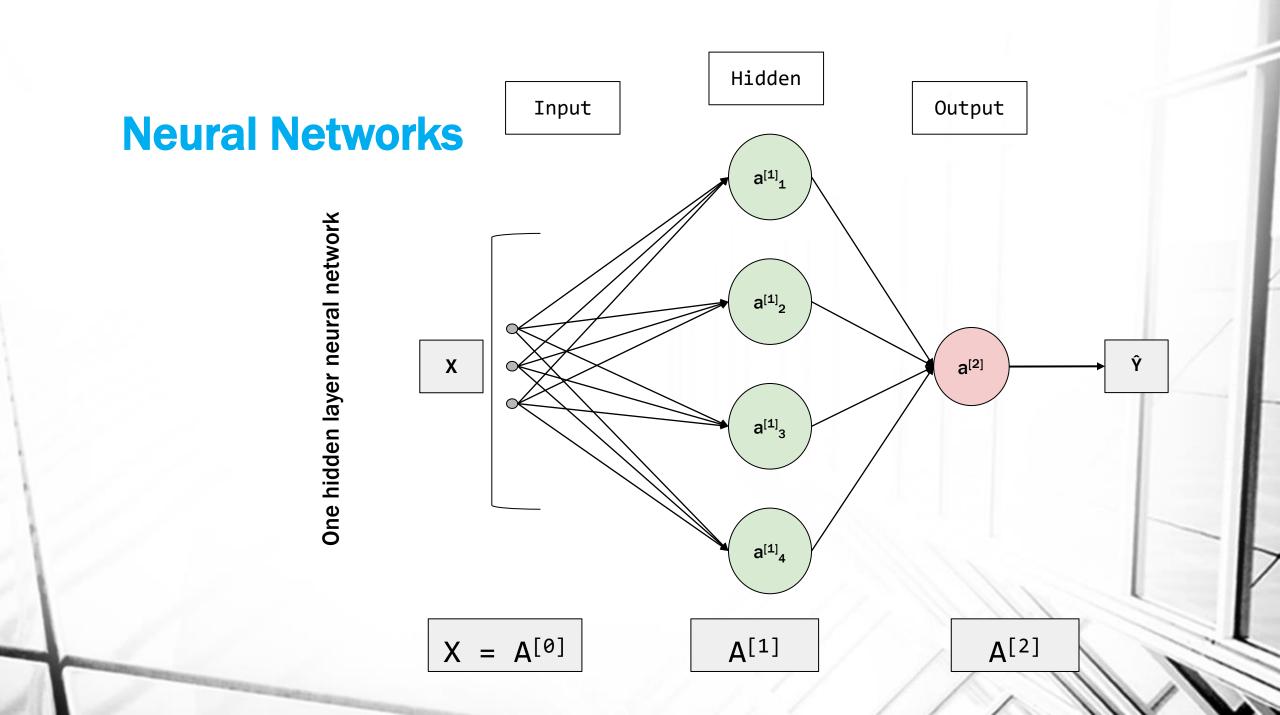
HMM for Automatic Speech Recognition



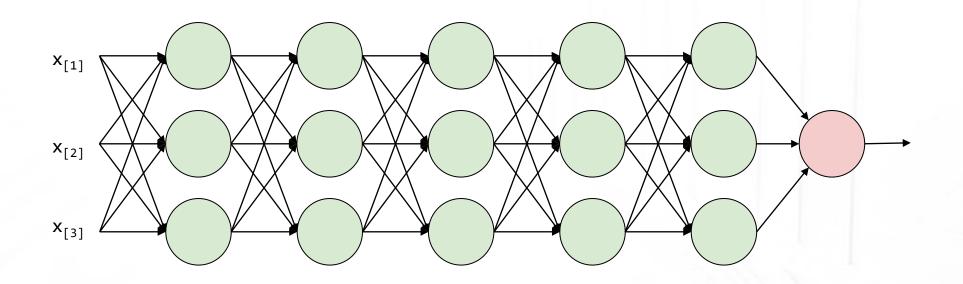
Perceptrons





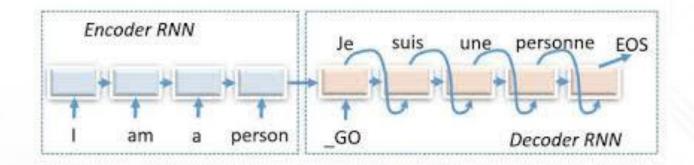


Neural Networks: going deeper



Transducing through NNs

- Networks can be used to express the intermediate states: Recurrent Neural Networks are used in this way
- States can be encoded and decoded, i.e. rewritten
- Decoding can be carried out locally (i.e. token-by-token) or globally (i.e. on a sentence-by-sentence basis)
- An Example: a transducer for Machine Translation



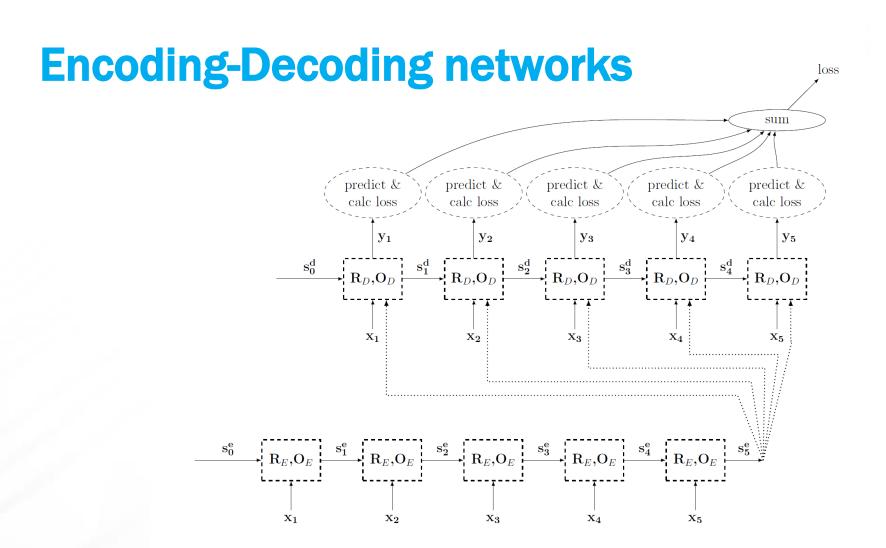


Figure 9: Encoder-Decoder RNN Training Graph.

Application of Encoding-Decoding networks

- Regression/Classification of input sequences
 - Time series for Predictions
 - Sentence Tagging
- Image Captioning (from images to natural language descriptions)
- Human-Machine Dialogue
- Human-Robotic Interaction
- Automatic Storytellig
- Video Making
- Instruction Learning